Representing data elements

February 20, 2003

Based on Chapter 12 in GUW, [Pagh03] Sec. 1 and 5.2, and [CLRS01] pp. 405-409

Advanced Database Technology, Spring 2003
In this lecture we ask: How does one store relations in a blocked memory?

<table>
<thead>
<tr>
<th>title</th>
<th>year</th>
<th>length</th>
<th>filmType</th>
</tr>
</thead>
<tbody>
<tr>
<td>Star Wars</td>
<td>1977</td>
<td>124</td>
<td>color</td>
</tr>
<tr>
<td>Mighty Ducks</td>
<td>1991</td>
<td>104</td>
<td>color</td>
</tr>
<tr>
<td>Wayne’s World</td>
<td>1992</td>
<td>95</td>
<td>color</td>
</tr>
</tbody>
</table>

Problems with updates:
What if we want to add “Episode 4” to “Star Wars” but there is not sufficient space in the block?
Overview of this lecture

- Storing fixed sized tuples
- Dealing with pointers
- Variable length tuples
- Updates
- Queues, stacks, and linked lists (I/O model and amortized analysis)
- Rebuilding due to deletions
Some terminology

- Attributes are stored as a sequence of bytes, called fields.
- Tuples are stored as a collection of fields, called records.
- Records are put together and are stored in blocks.
- A relation is a collection of records stored in blocks, called a file.
Attributes stored in fields

The schema of a relation specifies the type of attributes. This decides how much space is needed to store a relation. (It may be of variable size.)

- **CHAR(7)** a string of length 7 is stored in 7 bytes.
- **BIT(2)** is two bits, can be stored in two bits, but often a whole byte is used.
- \{RED, GREEN, BLUE, YELLOW\} is an enumerated type that can be stored as 00, 01, 10, 11, i.e. two bits is enough.
Variable sized data

Some attributes may not have fixed sized. If the size vary a lot for different tuples, then we do not want to allocate memory for all tuples to be able to store the maximum sized attributes.

However, that is what VARCHAR(n) in SQL does. $n + 1$ is the number of bytes allocated for the string, even if it may be shorter.

Two solutions:

- **Length + content**: $n + 1$ bytes allocated for a string of length $n$.

  $6$ $S$ $t$ $r$ $i$ $n$ $g$

- **Null-terminated string**: $n + 1$ bytes allocated for a string of length $n$.

  $S$ $t$ $r$ $i$ $n$ $g$ $\perp$
A tuple is stored in a record. The size is the sum of sizes of the fields in the record.

The schema is stored together with records (or a pointer to it). It contains:

- Types of fields
- Offsets for the fields within the record
- Size of the record
- Timestamps (last read, last updated)

The schema is used to access specific fields in the record.
Sometimes the following is essential:

- More efficient to read data at addresses that are multiples of 4 or 8.
- E.g., integers have to begin at a multiple of 4 (or 8).
- Blocks always start at a multiple of 4 (or 8).
  - Records and fields may also have to start at a multiple of 4.
Fixed-length records in blocks

Records are stored in blocks. Typically a block only contains one kind of records.

The block may have a header with info.:

- Index information, often in form of pointers. (More on indexes next lecture.)
- Type of tuples in the block.
- Offset table for the records in the block. Only needed if variable length records.
- Block ID.
- Timestamps.
Read the box on page 573 in the book and discuss:

- Do you agree with their conclusion?
- When are they right/wrong?
- How much time may it cost (in worst case) to follow their advise?
- When is it a good and when is it a bad idea to pack fields?
### Block and record addresses

Addresses or pointers to fields, records and blocks are often part of records and we have to deal with that in a special way. E.g., pointers to schemas and pointers used in index structures are stored in records.

Why addresses are different from other kind of data:

- Blocks are moved from secondary memory to main memory when it is used.
- Records may move, both within a block and from one block to another.
- Records may be deleted.
- Attribute values may change size, i.e. data move within a record.
Block addresses in main and secondary memory

Block address for blocks in main memory:
The block has a virtual memory address when it is loaded into a buffer in main memory.

Block address for blocks in secondary memory:
The block has no virtual memory address. The physical address has to be used. The physical address describes the physical location of the block.
Physical and logical addresses

**Physical address**
Describes physical location, i.e. which disk, which cylinder, which track etc.
Typical size is 8-16 bytes.

**Logical address**
A fixed length arbitrary string for each record. A table is used to map logical addresses to physical addresses.
Useful when records are moved, since only the map table has to be updated, and not the references to the record.
Structured addresses

Structured address
A combination of physical and logical addresses. E.g., only the physical address for the block. To find a record an offset table in the block or another kind of search in the block is needed.

Reasons why structured addresses are useful:

- A record can move within a block and still have the same structured address.
- When a record is removed it can be replaced by a tombstone that marks it deleted. The structured address can still be unchanged. When the record is looked up we know it is deleted.
Offset tables

How to organize an offset table:

- Grow the offset table from left to right and insert records from right to left. Since we do not know the size of the offset table when dealing with variable length records and when using tombstones.

- If the entries of the offset table are large enough references to other blocks can be stored. Useful when records are moved and we do not want to update the address.

- The tombstone can be stored in the offset table and the space used by the deleted record can be reused by another record.
How to manage pointers when blocks are moved between main memory (memory addresses) and secondary memory (database addresses).

- When in secondary memory database addresses are used.
- When in main memory database or memory addresses may be used.

Using memory addresses is more efficient. Otherwise translation is needed.

**Pointer swizzling**

When a block is in main memory pointers in the block can be swizzled (translated) from database addresses to memory addresses. A bit indicate the type of address.
**Swizzling strategies**

**Automatic Swizzling**
When a block is moved into main memory, all pointers in the block are swizzled if possible. All addresses to blocks currently in memory are stored in a translation table.

**Swizzling on Demand**
Pointers are swizzled when they are followed. When a block is moved into memory only the translation table is updated.

**No Swizzling**
Pointers are never swizzled. The translation table is used all the time.
Problem session: Swizzling

- Discuss the pros and cons of the three swizzling strategies:
  - Automatic Swizzling,
  - Swizzling on Demand, and
  - No Swizzling.
  
  When is it a good/bad idea to use them?

- What are the problems of returning blocks to disk? And how can they be solved?
Reasons why records not always have the same size:

- Fields of variable length. Attribute content vary in size.

- Repeating fields. An attribute that appear several times, but how many times is not specified by the schema.

- Records of variable format. When different tuples in a relation have different sets of attributes. E.g., if many attributes have no content.

- Enormous fields. Data like movies and pictures in the relation. The record may not fit into one block.
--- Fields of variable length ---

When a field has variable size we still have to be able to find all fields in the record. Since the offset cannot be read from the relation schema some extra information is stored in the record header.

Example of how it can be solved:

- Store fixed length fields first in the record.
- Store the total size of the record.
- Store offsets for variable sized fields (except the first).
Repeating fields

When a record contains a variable number of a field.
Store information in the record header to locate all occurrences of the field in the record.

A method to deal with fields of variable size and variable number of occurrences:

- Keep the record fixed size.
- Store variable length data on a separate block and use a pointer to it.
- Fixed sized records can be searched more efficiently. Less information is needed in the header. Moving records is easier.
- The number of I/O’s increase, since a pointer has to be followed.

Mixed strategies may be a good solution.
**Spanned records**

A record is called *spanned record* if it is split between two or more blocks.

**Reasons for spanned records:**

- Space utilization.
- Records larger than block.

For each fragment of a record extra information on where to find next and previous fragment is needed.
Binary, Large OBjectS = BLOBS

BLOBS can be images, movies, audio files and other very large values that can be stored in files.

Storing BLOBS

- Stored in several blocks.
- Preferable to store them consecutively on a cylinder for efficient retrieval.

Retrieving BLOBS

- A client retrieving a movie may not want it all at the same time.
- Retrieving a specific part of the large data requires an index structure to make it efficient.
We will look at three types of updates:

- Insertions of new tuples
- Deletions of tuples
- Tuple updates

What problems may arise when updates are performed on the database? Think of the different situations where we have:

- fixed length vs. variable length tuples
- no order vs. sorted tuples
Updates

Insert
No order: No problem, just find a block with enough space or use a new block.
Fixed order: May be a problem if there is not enough room in the correct block. Solutions: 1. Find space in nearby block and rearrange. 2. Create a overflow block.

Delete
Pack data in the block to prepare for new inserts. Remove overflow blocks if possible. Leave a tombstone if there may be pointers to the record.

Update
Fixed length: No problem.
Variable length: Same as for insert and delete. (But no tombstones.)