

# Software Programmable DSP Platform Analysis

Episode 6, Wednesday 4 May 2005, Ingredients

## Software Pipelining

Data & Resource Constraints

Resource Constraints in C67x

Loop Scheduling Without Resource Bounds

# Software Pipelining

- Modern computers can execute parts of many different instructions at the same time (not only DSPs).
- C67x can execute up to 8 instructions at the same time.
- Software pipelining is a technique used to schedule instructions from loops (mostly) so that multiple iterations of the loop execute in parallel.

# Data Dependence

If instruction *A* calculates a result that is used as an operand of instruction *B*, then *B* cannot be executed before *A* is finished.

# Resource Constraints

- **Function unit**  
If there are  $k_{fu}$  multipliers (adders, etc) on the chip, then at most  $k_{fu}$  multiplication (additions, etc) instructions can execute at once.
- **Instruction Issue**  
The instruction issue unit can issue at most  $k_{ii}$  instructions at a time.
- **Register**  
At most  $k_r$  registers can be in use at a time (often split into files).

## Resource Constraints in C67x (I)

An instruction of the following type scheduled on cycle  $i$  has the following constraints:

- **DP compare/ADDDP/SUBDP** (double precision float comparison)  
No other instruction can use the functional unit on cycles  $i$  and  $i + 1$
- **MPYI/MPYID/MPYDP**  
No other instruction can use the functional unit on cycles  $i, i + 1, i + 2$ , and  $i + 3$ .
- ...

[SPRU189F, p.4-12]

## Resource Constraints in C67x (II)

A *read/write hazard* exists when two instructions on the same functional unit attempt to read/write, to the register file on the same cycle.

An instruction of the following types scheduled on cycle  $i$  has the following constraints:

- **2-cycle DP**
  - A single-cycle instruction cannot be scheduled on that functional unit on cycle  $i + 1$  due to write hazard on cycle  $i + 1$ .
  - 2-cycle DP cannot be scheduled on that functional unit on cycle  $i + 1$  due to write hazard on cycle  $i + 1$ .

[SPRU189F, p.4-12]

## Resource Constraints in C67x (III)

- **4-cycle instruction**
  - A single-cycle instr. cannot be scheduled on that functional unit on cycle  $i + 3$  due to a write hazard on cycle  $i + 3$ .
  - Multiplication cannot be scheduled on that functional unit on cycle  $i + 2$  due to write hazard on cycle  $i + 3$ .
- **MPYI**
  - A 4-cycle instruction cannot be scheduled on that functional unit on cycles  $i + 4, i + 5, i + 6$ .
  - MPYDP cannot be scheduled on that functional unit on cycles  $i + 4, i + 5, i + 6$ .
  - Multiplication cannot be scheduled on that functional unit on cycle  $i + 6$  due to write hazard on cycle  $i + 7$ .
- ...

[SPRU189F, p.4-13]

## Resource Constraints in C67x (IV)

*Double-Precision Floating-Point Addition*

**ADDDP** (.unit) src1, src2, dst

stage	E1	E2	E3	E4	E5	E6	E7
read	src1_l src1_h						
written						dst_l dst_h	
unit in use	.L	.L					

If *dst* is the source for **ADDDP**, **CMPEQDP**, **CMPLTDP**, **CMPGTDP**, **MPYDP**, or **SUBDP**, the number of delay slots can be reduced by 1. These instructions read the lower word of the source one cycle before the upper word.

[SPRU189F, pp.4-22/24]

## We Do Need Automatic Scheduling!

With so many complex constraints, it quickly becomes a nightmare to find any nontrivial schedule for a given assembly program. Undoubtly we need good automatic techniques for handling this.

C16x incorporates an assembly optimizer containing a pipeline-aware automatic scheduler.

Manual techniques are given for highly fine-tuning your code with respect to pipeline in chapter 5 of Programmer's Guide. **[recommended reading]**

## Loop Scheduling

Without Resource Bounds

For simplicity assume that

- Every instruction can be computed in 1 cycle.
- There are no resource constraints (only data constraints)
- The number of iterations in the loop is fixed (like with matrix multiplications)

## Aiken-Nicolau Loop Pipelining

Loop Scheduling without Resource Bounds

- 1 Unroll the loop entirely.
- 2 Schedule each instruction from each iteration at the earliest possible time.
- 3 Find separated groups of instructions at given slope.
- 4 Coalesce the slopes.
- 5 Reroll the loop.

## Example: A loop to be software-pipelined

```
b ← V[0]
for i ← 1 to N
  a ← j ⊕ b
  b ← a ⊕ f
  c ← e ⊕ j
  d ← f ⊕ c
  e ← b ⊕ d
  f ← U[i]
  g: V[i] ← b
  h: W[i] ← d
  j ← X[i]
```

# Trivial Linear Schedule

```

b ← V[0]
for i ← 1 to N
  a ← j ⊕ b
  b ← a ⊕ f || c ← e ⊕ j
  d ← f ⊕ c
  e ← b ⊕ d || f ← U[i] || V[i] ← b || W[i] ← d || j ← X[i]
  
```

- Assumption: no hardware constraints (just data dependencies)
- V, U, W and X are disjoint (commonly required)

# Aiken-Nicolau Loop Pipelining

```

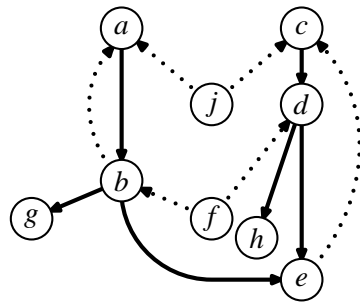
b0 ← V[0]
for i ← 1 to N
  ai ← ji-1 ⊕ bi-1
  bi ← ai ⊕ fi-1
  ci ← ei-1 ⊕ ji-1
  di ← fi-1 ⊕ ci
  ei ← bi ⊕ di
  fi ← U[i]
  gi : V[i] ← bi
  hi : W[i] ← di
  ji ← X[i]
  
```

After indexing accesses with iteration numbers.

# Data-Dependence Graph

```

b0 ← V[0]
for i ← 1 to N
  ai ← ji-1 ⊕ bi-1
  bi ← ai ⊕ fi-1
  ci ← ei-1 ⊕ ji-1
  di ← fi-1 ⊕ ci
  ei ← bi ⊕ di
  fi ← U[i]
  gi : V[i] ← bi
  hi : W[i] ← di
  ji ← X[i]
  
```

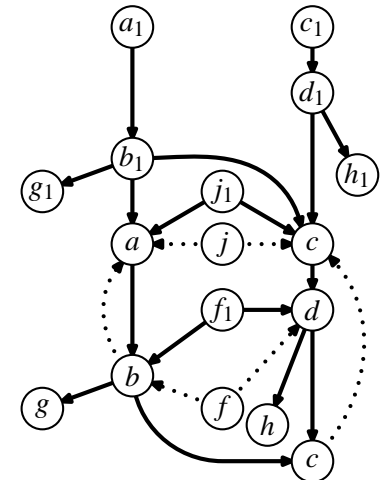


dotted: previous iteration deps  
solid: current iteration deps

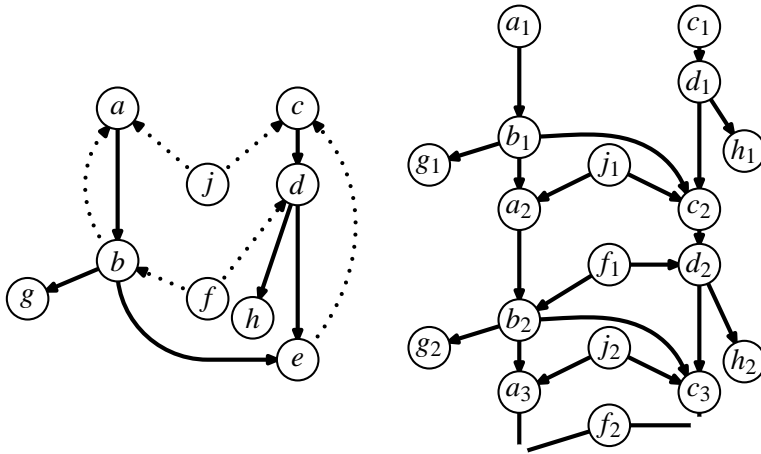
# Data-Dependence Graph Unrolled

```

b0 ← V[0]
for i ← 1 to N
  ai ← ji-1 ⊕ bi-1
  bi ← ai ⊕ fi-1
  ci ← ei-1 ⊕ ji-1
  di ← fi-1 ⊕ ci
  ei ← bi ⊕ di
  fi ← U[i]
  gi : V[i] ← bi
  hi : W[i] ← di
  ji ← X[i]
  
```



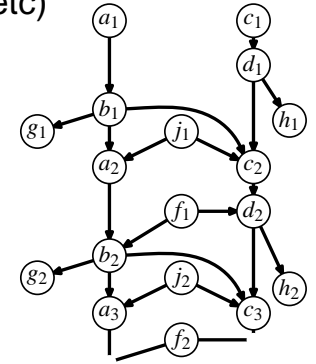
# Data-Dependence Graph Unrolled



# Schedule Completely Unrolled Loop

- Scheduling DAGs is easy: run each instruction as soon as all its predecessors have completed
- Do not take hardware limitations into account (unbounded concurrency, etc)

Cycle	Instructions
1	$a_1 c_1 f_1 j_1 f_2 j_2 f_3 j_3 \dots$
2	$b_1 d_1$
3	$e_1 g_1 h_1 a_2$
4	$b_2 c_2$
5	$d_2 g_2 a_3$



# Cycles/Iterations Tableau

Cycle	Instructions
1	$a_1 c_1 f_1 j_1 f_2 j_2 f_3 j_3 \dots$
2	$b_1 d_1$
3	$e_1 g_1 h_1 a_2$
4	$b_2 c_2$
5	$d_2 g_2 a_3$

	1	2	3	4	5	6	iterations
1	<i>acfj</i>	<i>fj</i>	<i>fj</i>	<i>fj</i>	<i>fj</i>	<i>fj</i>	
2	<i>bd</i>						
3	<i>egh</i>	<i>a</i>					
4		<i>cb</i>					
5		<i>dg</i>	<i>a</i>				
6		<i>eh</i>	<i>b</i>				
7			<i>cg</i>	<i>a</i>			
8			<i>d</i>	<i>b</i>			
9			<i>eh</i>	<i>g</i>	<i>a</i>		
10				<i>c</i>	<i>b</i>		
11				<i>d</i>	<i>g</i>	<i>a</i>	
12				<i>eh</i>		<i>b</i>	
13					<i>c</i>	<i>g</i>	
14					<i>d</i>		
15					<i>eh</i>		

# Cycles/Iterations Tableau: patterns

	1	2	3	4	5	6	iterations
1	<i>acfj</i>						
2	<i>bd</i>	<i>fj</i>					
3	<i>egh</i>	<i>a</i>					
4		<i>cb</i>	<i>fj</i>				
5		<i>dg</i>	<i>a</i>				
6		<i>eh</i>	<i>b</i>	<i>fj</i>			
7			<i>cg</i>	<i>a</i>			
8			<i>d</i>	<i>b</i>			
9			<i>eh</i>	<i>g</i>	<i>fj</i>		
10				<i>c</i>	<i>a</i>		
11				<i>d</i>	<i>b</i>		
12				<i>eh</i>	<i>g</i>	<i>fj</i>	
13					<i>c</i>	<i>a</i>	
14					<i>d</i>	<i>b</i>	
15					<i>eh</i>	<i>g</i>	

## Cycles/Iterations Tableau: patterns

	1	2	3	4	5	6	iterations
1	<i>acfj</i>						prologue
2	<i>bd</i>	<i>fj</i>					
3	<i>egh</i>	<i>a</i>					
4		<i>cb</i>	<i>fj</i>				
5		<i>dg</i>	<i>a</i>				
6		<i>eh</i>	<i>b</i>	<i>fj</i>			
7			<i>cg</i>	<i>a</i>			
8			<i>d</i>	<i>b</i>			new body
9			<i>eh</i>	<i>g</i>	<i>fj</i>		
10				<i>c</i>	<i>a</i>		
11				<i>d</i>	<i>b</i>		
12				<i>eh</i>	<i>g</i>	<i>fj</i>	
13					<i>c</i>	<i>a</i>	
14					<i>d</i>	<i>b</i>	epilogue
15					<i>eh</i>	<i>g</i>	

## Optimal Schedule

- The optimal schedule can be found in Appel (Fig. 20.7, p. 483)
- It may require some more massaging if values of a given variable from several iterations are live at the same time (for example *f* in the example). This is shown on Fig. 20.8

- The schedule returned is guaranteed to be optimal for a machine that fulfills its hardware requirements (8 concurrent instructions in this case).
- $7 + (N - 4) + 5$  cycles, while the original loop scheduled totally sequentially required  $9 * N$  cycles, while the trivial linear schedule (no instruction reordering) requires  $4 * N$  cycles.
- For  $N = 100$  the numbers are: 108, 900, and 400 respectively.
- On real machine it will surely take more cycles than 108.
- Software pipelining is difficult if there is control (branches) in the body of the loop.

## Resource Bounded Loop Pipelining

Outline of the algorithm:

- Check if the body of the loop can be scheduled in  $\Delta$  cycles.
- If this is possible finish.
- Otherwise increase  $\Delta$  and retry.

# Resource Bounded Loop Pipelining: Scheduling

- Take current instruction and schedule it at time  $t = t_0$
- If this violates constraints than increase  $t$
- Repeat this until  $t$  can be scheduled or  $r = t_0 + \Delta$
- If no success then there is no schedule of length  $\Delta$  (increase it).

# Example

Same Program as Before,  $\Delta = 3$

The machine can only perform one load instruction at a time.

```

b0 ← V[0]
for i ← 1 to N
  a_i ← j_{i-1} ⊕ b_{i-1}
  b_i ← a_i ⊕ f_{i-1}
  c_i ← e_{i-1} ⊕ j_{i-1}
  d_i ← f_{i-1} ⊕ c_i
  e_i ← b_i ⊕ d_i
  f_i ← U[i]
  g: V[i] ← b_i
  h: W[i] ← d_i
  j_i ← X[i]
    
```

An illegal schedule:

0		
1	$f_i \leftarrow U[i]$	$j_i \leftarrow X[i]$
2		

# Example

Same Program as Before,  $\Delta = 3$

We can try to move  $f_i$  one cycle back or forward:

```

b0 ← V[0]
for i ← 1 to N
  a_i ← j_{i-1} ⊕ b_{i-1}
  b_i ← a_i ⊕ f_{i-1}
  c_i ← e_{i-1} ⊕ j_{i-1}
  d_i ← f_{i-1} ⊕ c_i
  e_i ← b_i ⊕ d_i
  f_i ← U[i]
  g: V[i] ← b_i
  h: W[i] ← d_i
  j_i ← X[i]
    
```

Possibly extendable to a legal schedule:

0	$f_i \leftarrow U[i]$	
1		$j_i \leftarrow X[i]$
2		

0		
1		$j_i \leftarrow X[i]$
2	$f_i \leftarrow U[i]$	

# Example

Same Program as Before,  $\Delta = 3$

Actually we can go even one step further (backwards or forwards).

```

b0 ← V[0]
for i ← 1 to N
  a_i ← j_{i-1} ⊕ b_{i-1}
  b_i ← a_i ⊕ f_{i-1}
  c_i ← e_{i-1} ⊕ j_{i-1}
  d_i ← f_{i-1} ⊕ c_i
  e_i ← b_i ⊕ d_i
  f_i ← U[i]
  g: V[i] ← b_i
  h: W[i] ← d_i
  j_i ← X[i]
    
```

Possibly extendable to a legal schedule:

0		
1		$j_i \leftarrow X[i]$
2	$f_{i+1} \leftarrow U[i+1]$	

0	$f_{i-1} \leftarrow U[i-1]$	
1		$j_i \leftarrow X[i]$
2		

## Example

Same Program as Before,  $\Delta = 3$

Though not more. Two steps would clash with  $j$  again.

```
b0 ← V[0]
for i ← 1 to N
  ai ← ji-1 ⊕ bi-1
  bi ← ai ⊕ fi-1
  ci ← ei-1 ⊕ ji-1
  di ← fi-1 ⊕ ci
  ei ← bi ⊕ di
  fi ← U[i]
  g : V[i] ← bi
  h : W[i] ← di
  ji ← X[i]
```

An illegal schedule:

0		
1	$f_{i+1} \leftarrow U[i+1]$	$j_i \leftarrow X[i]$
2		

0		
1	$f_{i-1} \leftarrow U[i-1]$	$j_i \leftarrow X[i]$
2		

## Properties of the Algorithm

- The algorithm does such search in a greedy manner for consecutive instructions
- Typically it will start with instructions that are most dependent on other instructions, to increase a chance of earlier termination (relatively independent instructions are easy to schedule).

- The algorithm is not guaranteed to find an optimal solution
- It is not even guaranteed to find a solution of size  $\Delta$  when one exists.
- It may also find a schedule for which a register allocation fails (and then it needs to be run again, as spills change scheduling)
- It may not terminate even! So often in practice it stops examining a given  $\Delta$  after some time, and tries the next one.
- The consolation is that it is reported to work very well in practice.

## Sometimes Cl6x Gives up on Pipelining

- If a value is live in a register for more than the number of cycles in the loop (we have explained how to do it...)
- If the loop contains very complex conditions in the body.
- If the loop contains function calls (other than intrinsics or inlined functions)
- If the loop contains break statements (rewrite to use ifs).

: source Programmer's guide p. 2-54



“If” statements can only be used around the code that updates memory and around variables whose values are calculated inside the loop, but only used outside the loops (we know that this is keeping the induction variables linear...).

: source Programmer's guide p. 2-54

**Thanks for Attention.  
Good Weekend!**